

## **IN THE SPECIFICATION**

***Kindly replace the paragraph beginning on line 32 of page 4 and extending to line 10 of page 5 with the following:***

FIG. 1 illustrates an embodiment of how the RSL language may be utilized by an end-user, sitting at a computer terminal, desiring to create a robotic web presentation. FIG. 1 illustrates a snapshot image of a computer terminal display screen 10 running a program for creating a robotic presentation. As shown, A palette of selectable icons [[20]] 05 for defining desired robotic actions are defined in an upper portion of the display screen 10 including a “run” icon 11, “jump” 13, “smile” 15, and so on. The user would create a robotic presentation by simply grabbing and dropping the selectable icons in a desired presentation sequence 35. The snapshot image of FIG. 1 illustrates that the end-user has created a partial robotic web presentation consisting of four icons commanding the robot to first “jump” 36, “smile” 37, sigh” 38 and “roll eyes” 39 in that order as indicated by the time axis. Using the simplified icon driven approach, a robotic presentation may be created in a straight forward easily understood manner.